5G-MOBIX

Project Overview & Key Achievements

Kostas Trichias (Technical Coordinator – WINGS ICT Solutions)
5GPPP TB eWorkshop, May 26th, 2020





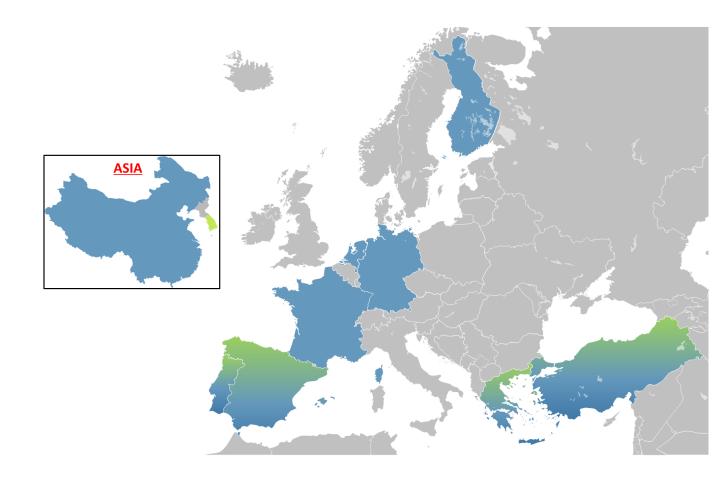
Layout

- Quick overview
 - Cross-Border Corridors
 - Use cases
 - Vehicles
- Key Achievements
 - 5G Architecture
 - Cross-Border Challenges
 - Deployment & Integration methodology/planning
 - KPI definition (Technical, Business, User Acceptance)
- Roadmap (+ Covid-19 impact)



Overview of 5G-MOBIX CBCs / TSs

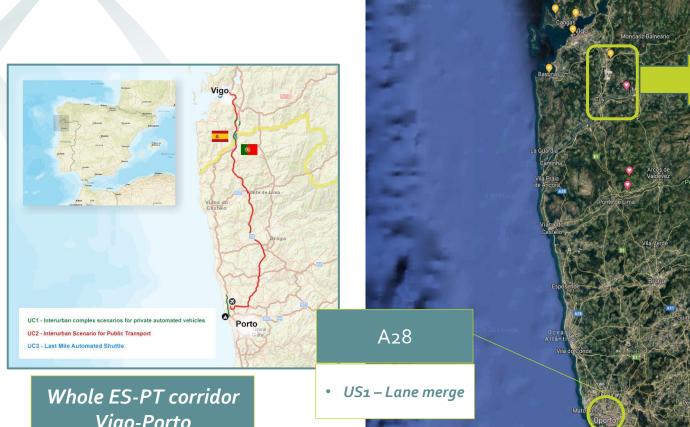
- 2 Cross-Border Corridors (CBC)
- 4 complementary European Trial Sites (TS)
- 2 complementary Asian Trial Sites (TS)
- 5 Use case categories based on 3GPPTS 22.186, focusing on x-border operation
- 24 SAE L4 automated vehicles
- **30** 5G gNBs
- NSA Architecture (potential for evolving to SA)





Cross-Border Corridors

ES-PT CBC Overview. Location





AP9-A55

US1 - Lane merge US1 - Overtaking US1, US2 - HD maps

Old Bridge ES-PT CB

US₃ - Cooperative automated operation US₃ – Remote control

New Bridge ES-PT CB

US1 - Lane merge **US1** - Overtaking US1, US2 - HD maps

Vigo-Porto

- US2 4k bus monitoring
- US2 Multimedia service for passengers



Spain-Portugal Cross-Border Corridor.

• The Spanish-Portuguese corridor connects the cities of Vigo and Porto (250 Km,) and use next roads/highways:

• Spain:

- City of Vigo (4 Km).
- A55 (10 Km).
- AP₉ (5 Km).

• Portugal:

- A3 (5 Km).
- N13 (1km).
- A28 (7 Km) near the Porto Airport and Boat Passenger Terminal.

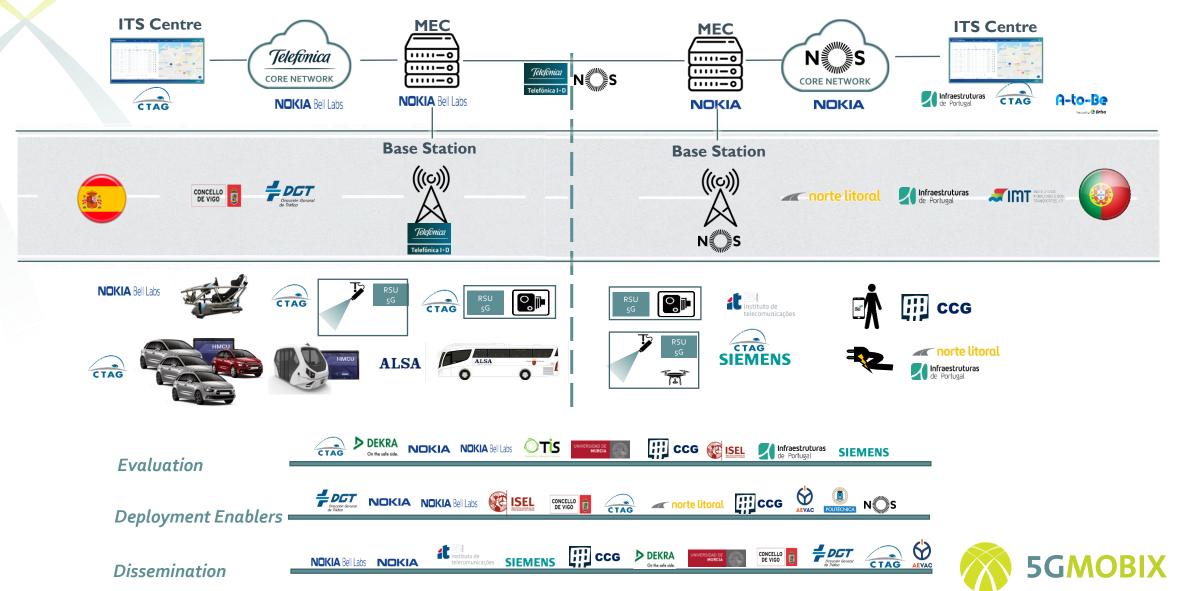
• Cross-Border:

- Located in the border of the north of Portugal with Spain.
- Established by the Minho/ Miño river, disposing of two bridges providing the road infrastructure serving trucks, cars and pedestrians.
- International trade as well as large passenger commuting flows are of great importance and provide ideal conditions for the execution of diversified trials to showcase the advantages offered by the 5G connectivity to CCAM use cases.





ES-PT CBC Overview. Stakeholders

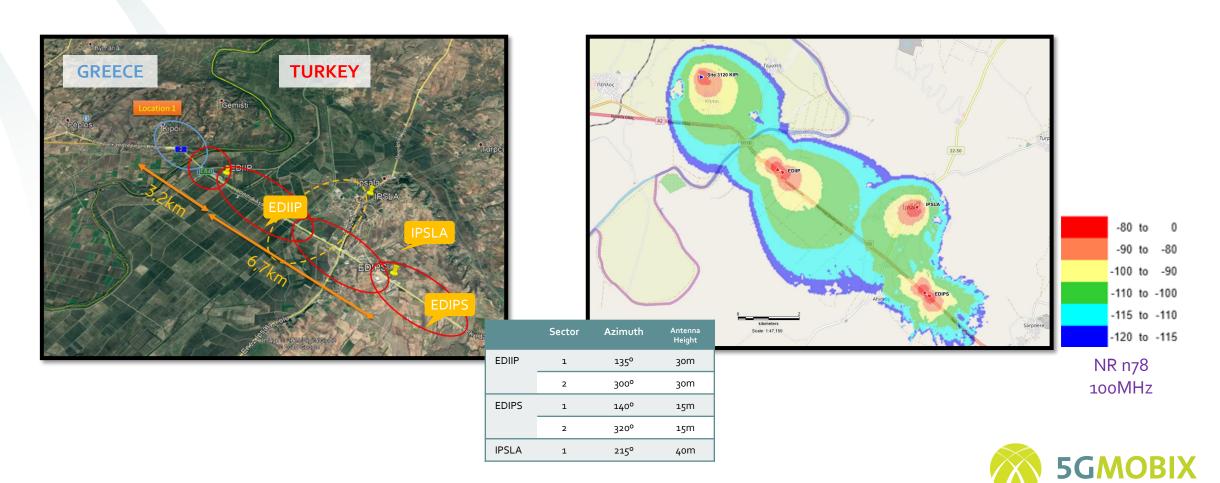


Greece-Turkey Border Харманли Lyubimets Любимец Mustafapaşa Свиленград Pinarhisar Kumçiftliği Ορεστιάδα Lüleburgaz Babaeski o Çerkezköy GÜMRÜK KAPIS Arnavutköy Maslak Silivri İstanbul Büyükçekmece Tekirdağ Marmaraereğlisi Sultan Dedeağaç εξανδρούπολη Malkara Kumbağ http://trakya.ticaret.gov.tr/saha-canli-goruntu/ipsala



Cross-border Trial Location

Ipsala (TR) – Kipoi (GR)



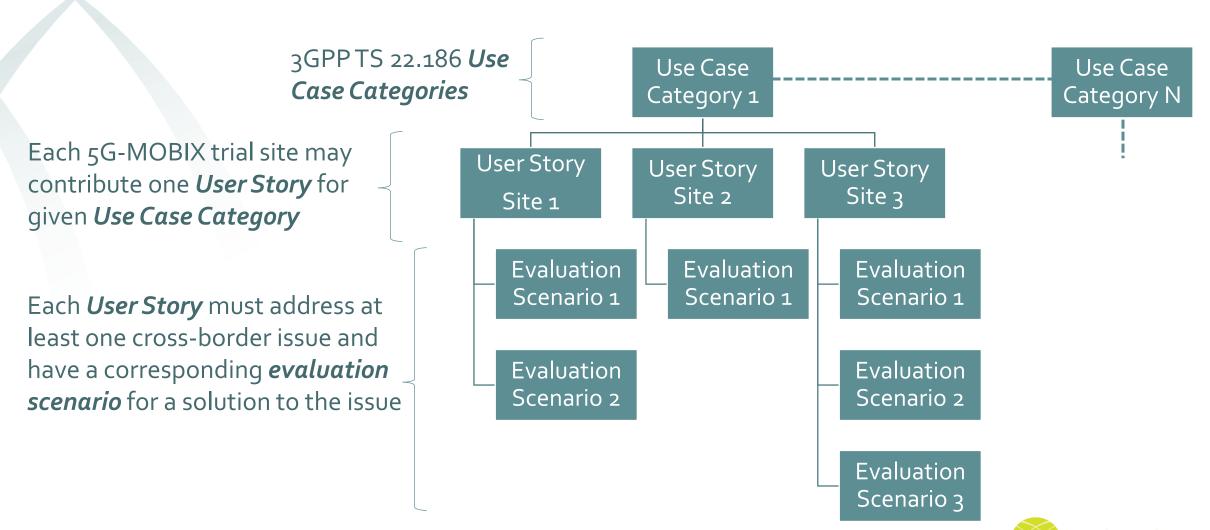
Key Stakeholders

Partner	Role				
FORD OTOSAN	Truck Manufacturer				
imec	C-V2X Technology Developer				
TURKCELL TEKNOLOJI	MNO, Network and Frequency Provider				
€ COSMOT€	MNO, Network and Frequency Provider				
INTRASOFT INTERNATIONAL	Technology Integrator & Software Developer				
WINGS IN SOLUTION	Software Tools Developer & IoT, AI Expert				
ERICSSON GR	5G Technology Provider				
ERICSSON ≢ TR	5G Technology Provider				
(ICCS	CCAM / 5G Experts & KPI Evaluation Experts				
BILGEM	Research institute				
	Hellenic Ministry of Infrastructure and Transport (GR)				
Ministry of Digital Policy, Telecommunications and Media (GR)					
	Turkish Ministry of Transport and Infrastructure (TR)				



5G-MOBIX Use Cases

5G-MOBIX Use Case Taxonomy



5G-MOBIX UCC/US overview & TS contributions

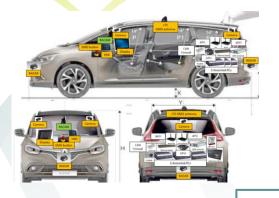
- Different architecture / technology may be used at different sites evaluating their performance
- Focus on cross-border operation at the two CBC
 - Spain-Portugal (ES-PT)
 - Greece-Turkey (GR-TR)
- Local TS have been selected to contribute and enable the CBC trials (providing SW, components, alternatives, etc.)
- Extended evaluations requiring controlled environments also performed at the TS

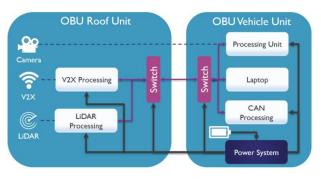
CBC: Cross-Border Corridor TS: (Local) Trial Site

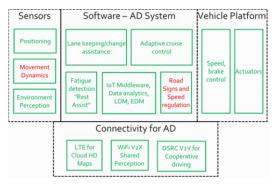
Trial site	Advanced Driving	Vehicles Platooning	Extended Sensors	Remote Driving	Vehicle QoS Support
ES-PT	Complex manoeuvres in cross-border settings			Automated shuttle remote driving across borders	Public transport with HD media services and video surveillance
GR-TR		Platooning with "see what I see" functionality in cross-border settings	Extended sensors for assisted border-crossing		
DE		eRSU-assisted platooning	EDM-enabled extended sensors with surround view generation		
FI			Extended sensors with redundant Edge processing	Remote driving in a redundant network environment	
FR	Infrastructure-assisted advanced driving				QoS adaptation for Security Check in hybrid V2X environment
NL	Cooperative Collision Avoidance		Extended sensors with CPM messages	Remote driving using 5G positioning	
CN	Cloud-assisted advanced driving	Cloud-assisted platooning		Remote driving with data ownership focus	
KR				Remote driving using mmWave communication	Tethering via Vehicle using mmWave communication

5G-MOBIX Vehicles

Overview of 5G-MOBIX CBCs / TSs – Vehicles



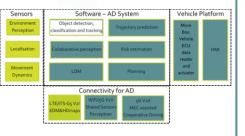




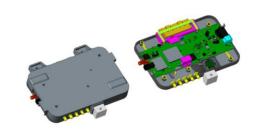




- Different functional architecture utilized
- Various OBU versions and functionalities
 - Starting from Rel.14 support and migrating to Rel.15 during the project lifetime
- Supporting different Augmented Automated Driving Functions









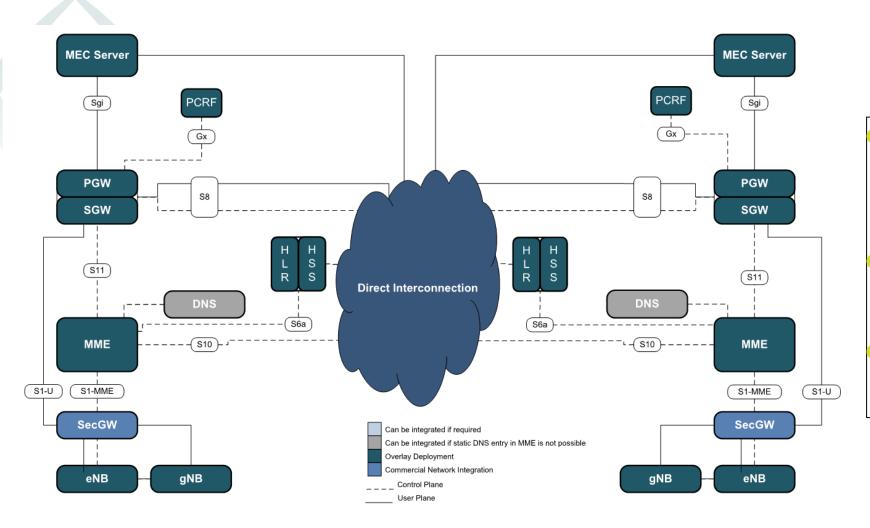




Key Achievements

5G Architecture

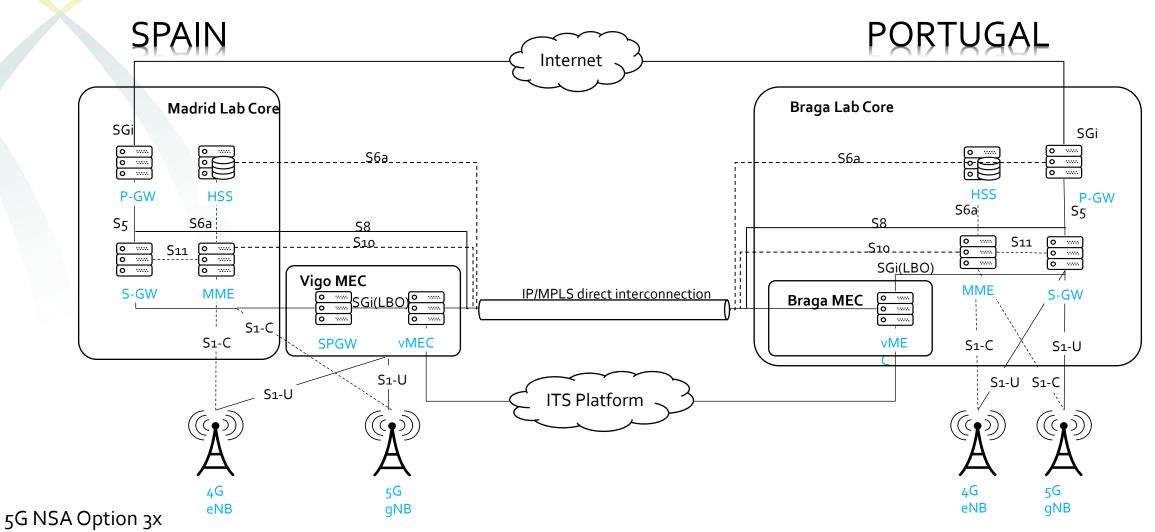
Common 5G architecture defined for the CBCs



- Direct interconnection between neighbouring PLMNs
- UP & CP traffic over the direct interconnection
- HR & LBO roaming options available



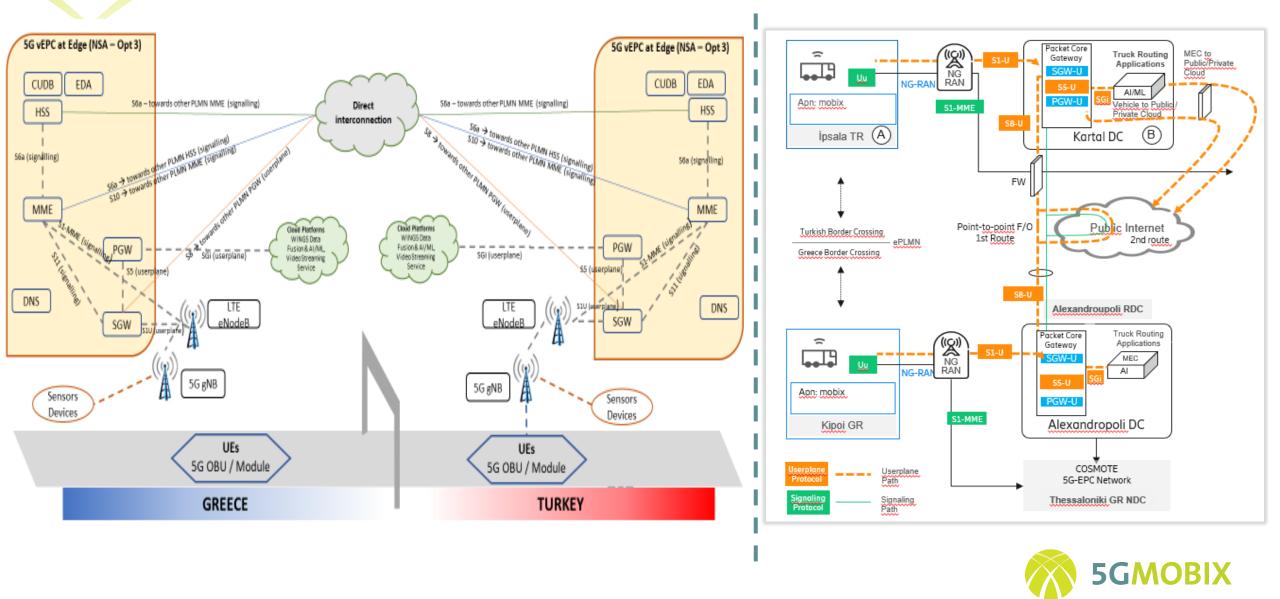
ES-PT 5G Architecture



ETSI MEC deployed with distributed SGW with Local Breakout (SGW-LBO)



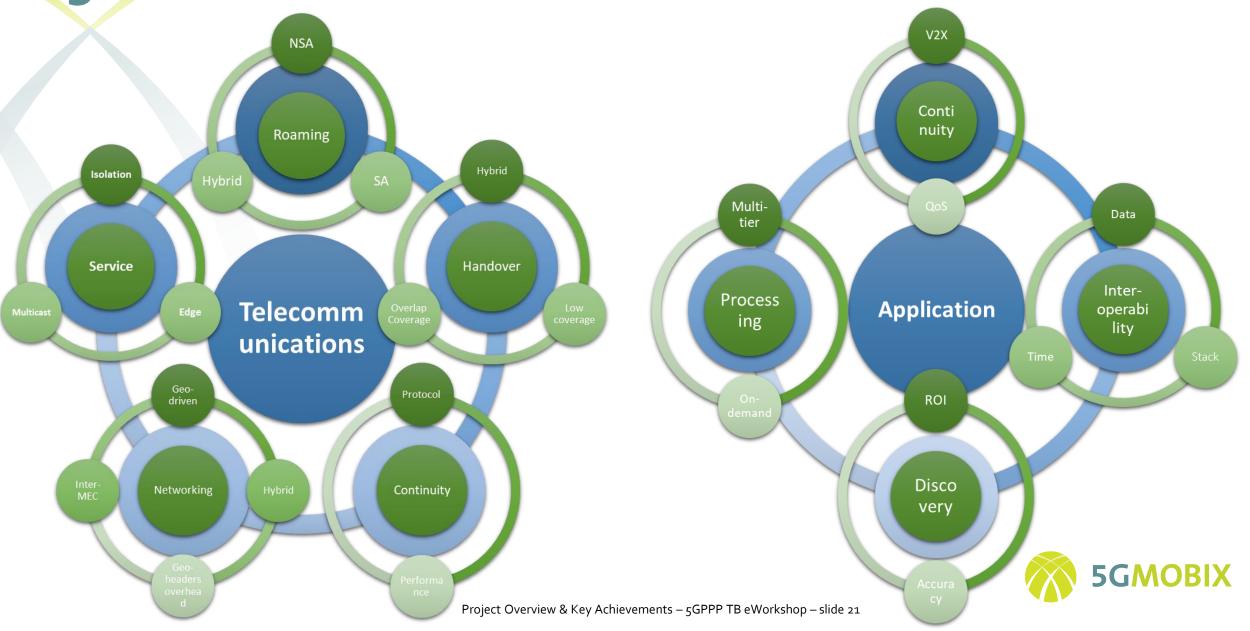
GR-TR 5G Architecture



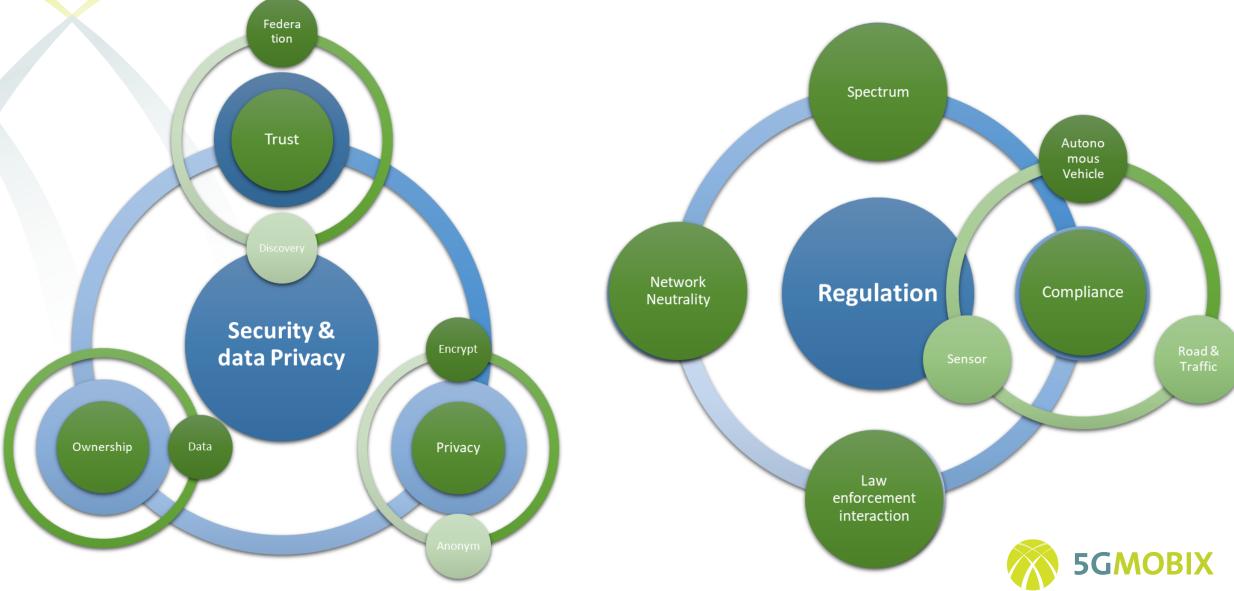
Key Achievements

Cross-Border Challenges

5G-MOBIX Cross-border issues - Overview



5G-MOBIX Cross-border issues – Overview

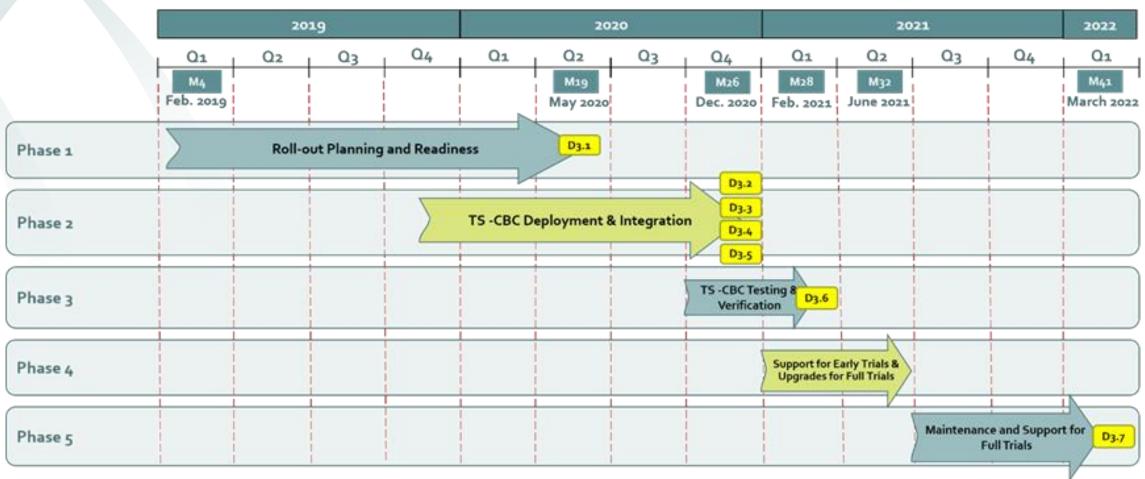


Key Achievements

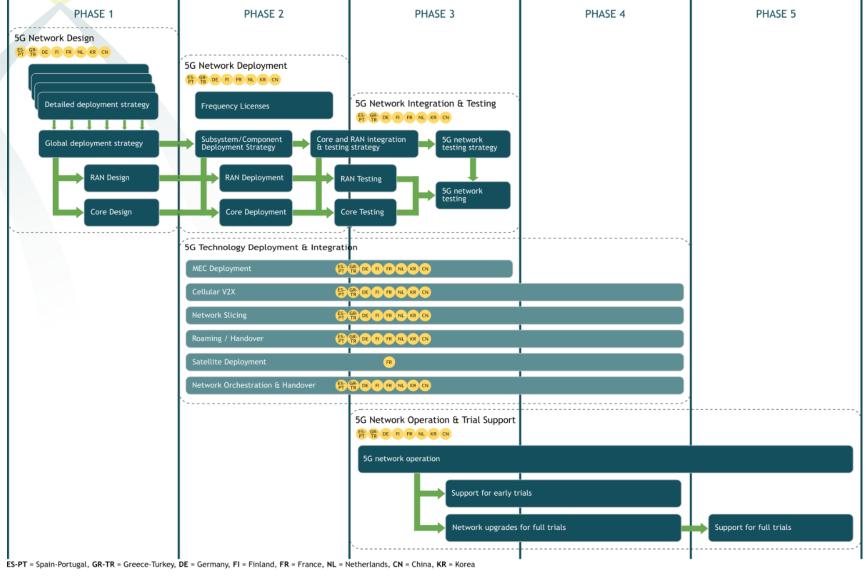
Deployment & Integration methodology/planning

5-Phase Roll-out plan

Centralized plan for CBC/TS deployment, integration and verification



Deployment Methodology



- Individual detailed planning of main tasks following the 5-phase approach, for each major component
 - 5G Network
 - ITS/RSI Infra
 - Vehicles/OBUs
 - Evaluation & Data management infra
 - Integration & Verification
- Individualized actions per CBC/TS
- Common check-points for progress monitoring



Key Achievements

Evaluation Approach & KPI Definition (Technical, Business, User Acceptance)

Evaluation Scope and Objectives

Technical evaluation

OBJECTIVE: To comprehensively evaluate the technical performance of technologies and solutions implemented

Impact assessment (QoL/Business impacts – Cost/benefit analysis)

OBJECTIVE: To assess the potential business and societal impacts of the systems and applications demonstrated in the cross-border corridors and trial sites.

User acceptance

OBJECTIVE: To evaluate acceptability and acceptance rates of different kinds of mobility services.



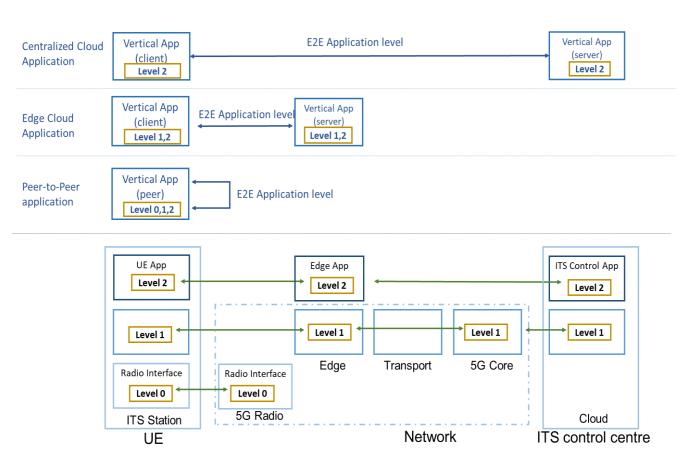
Technical Performance Evaluation

High Level Objectives

- Assess network capabilities UCC/USagnostic
 - End-to-end / Per network segment
- Assess user perceived performance UCC/US-specific
 - Impact of cross-border mobility on CCAM application-level

Measurements

- Layered
 - Access (e.g., radio parameters)
 - Transport (Network/IP Layer)
 - Application (E2E: UE-UE, UE-Edge, UE-Cloud)
- Per Segment
 - Access Edge Transport Core -Cloud



Data Collection Levels and Network Segments



Technical Performance KPIs

General KPIs

- User experienced data rate / Throughput
- End to end Latency
- Control / User plane Latency
- Reliability
- Position Accuracy
- Network Capacity
- Mean Time To Repair

Handover KPIs

- NG-RAN Handover Success Rate
- Application Level Handover Success Rate
- Mobility interruption time

Taking into account 5G-PPP, 3GPP and 5G-AA KPI frameworks...

	User Story	TE-KPI1.1 User experienced data rate (UL / DL)	TE- KPI1.3 E2E Latency	TE-KPl1.6 Reliability	TE-KPI1.7 Position Accuracy	TE-KPI2.3 Mobility Interruption Time	TE-KPl2.2 Application Level Handover Success Rate ⁷
UCC-2 : Vehicles UCC-1 : Advanced Driving	Complex manoeuvres in cross-border settings	0.2 / 0.2 Mbps	200 ms	99,9%	1 - 5 m	< 10 S	99-100%
	Infrastructure- assisted advanced driving	100 / 50 Mbps	<u>5</u> - 20 ms	100.00%	0.1 m	< 5 s	N/A
	Cooperative Collision Avoidance	1 /1 Mbps (10-20 Mbps for high resolution raw data DL)	< 10 ms	90-99.99%	0.2 M	< 15	99-100%
	Cloud-assisted advanced driving	100 / 100 Mbps	20 - 50 ms	90-99.99%	0.2 M	< 10 5	N/A
	Platooning with "see what I see" functionality in cross-border settings	100 / 50 Mbps	20 ms	99% – 99.999%	0.5 M	< 40 ms	99-100%
	eRSU-assisted platooning	200 / 100 Mbps	40 ms	100.00%	0.2 M	40 ms	N/A
	Cloud assisted platooning	100 / 100 Mbps	20 - 50 ms	90-99.99%	0.2 M	< 10 5	N/A
UCC-3: Extended Sensors	Extended sensors for assisted border crossing	100 / 200 Mbps	20 - 50 ms	100.00%	0.2 M	50 ms	N/A
	EDM-enabled extended sensors with surround view generation	200 / 100 Mbps	40 ms	100.00%	0.2 M	40 ms	99-100%
	Extended sensors with redundant Edge processing	15 / 15 Mbps	100 ms	99.99%	N/A	10 - 80 ms	99-100%
	Extended sensors with CPM messages	10 / 10 - 20 / 20 Mbps	< 20 ms	90-99.99%	N/A	100 ms	99-100%
OCC-4:	Automated shuttle remote driving across borders	10 / 1 Mbps	100 - 200 ms	99,9%	1-5 M	< 10 5	N/A
							BIV



Impact assessment & User Acceptance metrics

Business

- Customer need
- Costs
- Revenues
- Progress towards commercial deployment

Quality of Life

- Personal mobility
- Traffic efficiency
- Traffic safety
- Environment

User Acceptance

- General Technology Acceptability
 - Acceptance Intention (statement of interest), Perceived Technology Usefulness, Perceived Technology Ease-ofuse, Affinity for Technology Interaction, Acceptability difference between prior and post-contact with technology
- Trust on the system
- Systems usability
- Error tolerance



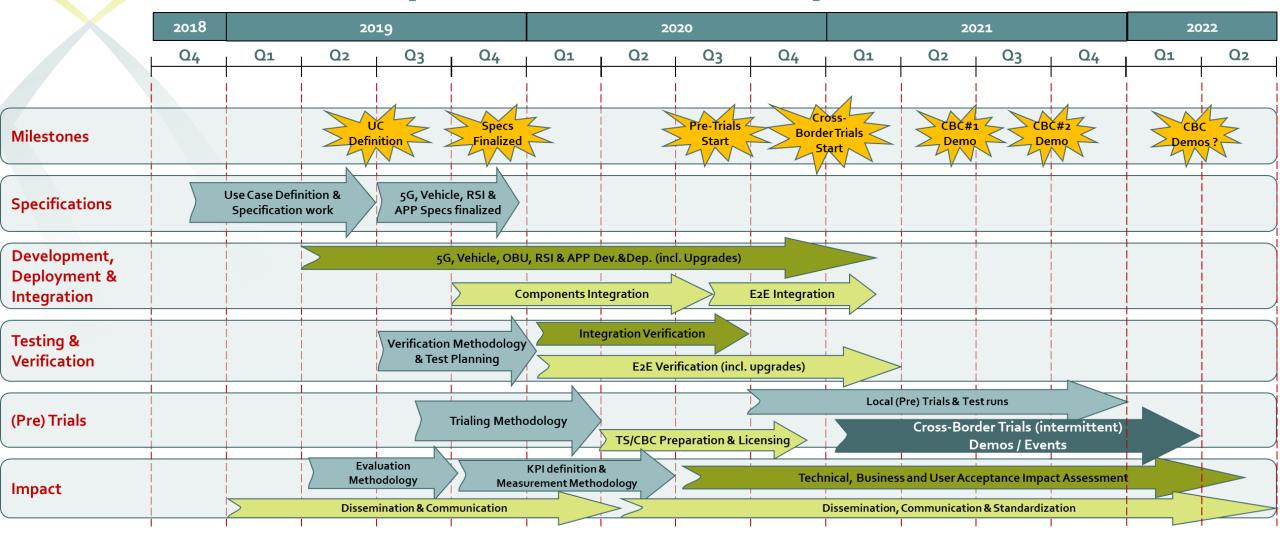
5G-MOBIX Roadmap

Impact on 5G-MOBIX Roadmap

- COVID-19 measures have impacted the project timeline in several ways
 - 5G-chipset delivery
 - 5G-network equipment delivery
 - Ability to work "in the field" for deployment tasks
 - Ability to work in factories/labs for vehicle, RSU, OBU development
 - Ability to perform site visits for measurements, assessments and design
- Additional challenges
 - Change of Project Coordinator
 - Turmoil at GR-TR borders (fugitive crisis)
- A project extension of 9 months has been requested



5G-MOBIX updated Roadmap





Thank you

Questions?



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